## DEPARTMENT OF ELECTRNICS & COMMUNICATION ENGINEERING, KITSW

#### COURSE: **U14EI 205 - BASIC ELECTRONICS ENGINEERING** ECE-I, Semester-II, 2015-16

# ASSIGNMENT-7 HINTS & SOLUTIONS (PART-3 – of - 3)

- 6. The true value of the voltage across a resistor is 80V. However, when a 0-100V meter is employed, the measurement reading obtained is 79V. Calculate:
  - (i) absolute error
  - (ii) relative error as function of measured value
  - (iii) relative error as function of fsd

#### **Solution:**

- <u>Given data</u>: True voltage = 80V, Measured voltage = 79 V Voltmeter fsd = 100V
  - (i) Absolute error (e) = Measured value- True value = 79-80= -1V
  - (ii) Relative error is % error.

Relative error as a function of measured value =  $\frac{\text{Measured value-True value}}{\text{Measured value}} \times 100\%$ 

$$=\frac{79-80}{79}$$
 x 100 % = - 1.266 %

(iii) Relative error as a function of fsd =  $\frac{\text{Measured value-True value}}{\text{fsd}} \times 100\%$ 

$$=\frac{79-80}{100} \times 100\% = -1\%$$

7. With a neat sketch, explain the principle of permanent magnet moving coil (PMMC) instrument and discuss briefly the errors in PMMC.

For deflection type instruments, three operating forces are required. (i) Deflecting force (ii) controlling force (iii) Damping force. Deflecting force 8 -> when a current floros the coil, a magnetic flux -> This electro-magnetic flux interacts with the flux due to permanent magnet -> A torque called deflecting torque is produced. -> As a result, the coil starts refating and along with it, the pointer moves over the scale K-1-X let B = Magnetic flux density (T) due to permanent magnet 2sten a current I flores through a one-turn coil the force of length (1), then the force F excepted on each side of the coil is F = BIL Newtony Then total force acting on both sides of the coil of N. F = 2BIR-N frens The deflecting torque Td = 2BILN.Y (N-M) Ta = (BILN(2r) T<sub>d</sub> = BILND. D-> dia gcoil. Ta= NABI ; A > effective

Controlling force The controlling force in PMMC instrument is provided by spinal springs. Scale untur fundance -> Spring material must be non-magnetic Pointer to avoid any magnetic field influence fora 7 on controlling force 1 Corl -> springs are made of phosphor Bronze Sprival spring - , when these is no current in the coil, the spring keeps the coil and the pointer at zero position -> when current flows, the coil rotates and the springs "voind up" -> As the coil rotates, the restoring force (torque) provided by the spring springs goes on uncreasing. -> The coil and pointer stop rotating at a point stere deflecting torque (Td) = controlling torque (Tc) = KO BINA Here K = spring constant (Nm/deg) O = angular deflection of the pointer (deg) O= BINA > O XI ie the pointer deflection is always proportional to the coil current (I) and hence Scale is linear or uniformly divided //

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Damping force or Torque -) The pointer deflects to a position where TC=Td -> The pointer and the coil tend to oscillate for some time before settling down at final possition. - Lack of Damping causes the pointer to oscillate Pointer children Pointer position Oscillation without Damping Final position with damping time, -> In prime instruments, the damping force is normally provided by eddy currents -> The coil former (core) is constructed of Aluminium, a non-magnetic conductor. -> Eddy currents are introduced in the coil former set up a magnetic flux that opposes the coil motion and thus damps the oscillations of the coil. specifications. The d'Arronval movement (or meter) or punc instrument is specified on terms of ils « current sensitivity" or full scale deflection current and the coil resistance. - The most sensitive d'Arronval meter gives f.s.d with a coil current of 254A

### **Advantages of PMMC instruments:**

- 1. Linear scale ( the scale is uniformly divided)
- 2. High torque -to- weight ratio (high accuracy can be achieved)
- 3. Very low power consumption (25  $\mu$  W -200  $\mu$  W)
- 4. Free from hysteresis errors
- 5. Wide range of currents can be measured with the help of shunts
- 6. Wide range of voltages can be measured with the help of series multipliers

#### **Disadvantages of PMMC instruments:**

Suitable for dc measurements only Aging of permanent magnet and control springs introduces errors Friction due to jewel-pivot suspension Instrument cost is high

## **Errors in PMMC instruments:**

- Errors due to friction:
  - o To reduce errors due to friction, the torque-to-weight ratio is made high
- Errors due to temperature: Basic PMMC is sensitive to temperature.
  - o The magnetic field strength decreases with increase in temperature
  - o The spring tension decreases with increase in temperature
  - o The coil resistance increases with increase in temperature
- Errors due to aging:
  - Weakening of permanent magnet causes less deflection for a given current
  - Weakening of control spring causes more deflection for a given current

## 8. With the help of circuits explain how PMMC can be used as

- (i) an ammeter
- (ii) multirange ammeter using Aryton shunt with necessary equations
- (iii) voltmeter
- (iv) multirange voltmeter with necessary equations

#### (refer to class notes....)

Those who missed regular classes are advised to take notes from their friends who attended.

- 9. With required circuits and necessary computations, explain how a PMMC movement of range 0-25mA, with an internal resistance of  $20 \Omega$ , can be
  - (i) extended to a range of 0-100mA; and
  - (ii) converted into an Voltmeter of range 0-10V.



- 10. Two resistors  $R_1=140k\Omega$  and  $R_2=100k\Omega$  are connected in series across 12V supply. A voltmeter on a 10V range is connected to measure the voltage across the resistor ' $R_2$ '. Calculate
  - (i) actual value of voltage across  $R_2$ , (ii) measured voltage across  $R_2$  with voltmeter having sensitivity of  $20k\Omega/V$ , (iii) measured voltage across  $R_2$  with voltmeter having sensitivity  $200k\Omega/V$ , (iv) % error in both the above cases What is your comment on the result with reference to sensitivity of the voltmeters used?

Selution:  
(i) Arthual Vettage across 
$$R_2$$
.  
 $V_0 = \frac{R_2}{R_1 + R_2} \times V = \frac{100k}{(100k + 140k)} \times 12V$   
 $= \frac{100}{240} \times V = \frac{100k}{(100k + 140k)} \times 12V$   
 $= \frac{100}{240} \times V = \frac{100k}{12} \times 12V$   
 $= \frac{100}{240} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{200k} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{200k} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{200k} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{100k} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{100k} \times 12 = \frac{5}{2}V$   
 $= \frac{100}{100k} \times 12 = \frac{5}{20}V$   
 $= \frac{100}{100k} \times 120k$   
 $= \frac{100}{100k} \times 120k$   

The doop across 
$$\operatorname{Reyg} = \frac{\operatorname{Reyf}}{\operatorname{R_1} + \operatorname{Reyg}} \times 12 V$$
  
 $V_2 = \frac{95238k}{(140 + 95238)k} \times 12 V = \frac{4.958}{12} V$   
 $e^{12} V = \frac{95238k}{(140 + 95238)k} \times 12 V = \frac{4.958}{12} V$   
Hence error in voltmeter scading (e) =  $\frac{\operatorname{measured}}{\operatorname{True}} = \frac{4.858}{2} \times 100 \ ^{\circ}{}_{\circ}$   
 $e = \frac{4.858}{5} \times 100 = -2.84 \ ^{\circ}{}_{\circ}$   
 $\times \operatorname{voltmeter}$  sitt  $S = 20 \ k_2 \ ^{\circ}{}_{\circ}$  reads voltage across  $\operatorname{R_2}$  with  $-22.58 \ ^{\circ}{}_{\circ}$  correr  
 $\times \operatorname{voltmeter}$  scade  $\sqrt{4} \times 100 \ ^{\circ}{}_{\circ}$   
 $= \frac{4.858}{5} \times 100 = -2.84 \ ^{\circ}{}_{\circ}$ 

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