

## Causality & Memory:

- ✓ A system whose present output (response) requires future inputs are termed as non-causal.
- ✓ what makes the LCCDE non-causal.
  - If the least delayed output is  $y[n]$  then terms like  $x[n+k]; k > 0$  will make it NC

Ex:

- ✓  $y[n] - 3y[n-2] = x[n] \rightarrow$  causal
- ✓  $y[n] - 3y[n-2] = x[n+2] \rightarrow$  noncausal
- ✓  $y[n+1] - y[n] = x[n+1] \rightarrow$  causal
- ✓  $y[n+2] - y[n+1] - y[n] = x[n+3] \rightarrow$  Noncausal.

Memory  $\begin{cases} \text{static or instantaneous} \\ \text{dynamic} \end{cases}$

If the response of the system at  $n=n_0$  depends only on the input at  $n=n_0$  and not at any other times (past & future), the system is called static or instantaneous.

Ex:

$$y[n] = 2x[n] \rightarrow \text{static}$$

$$y[n] = 2x[n-1] \rightarrow \text{dynamic}$$

$$y[n-1] = 2x[n-1] \rightarrow \text{static}$$

$$y[n-1] = 2x[n-2] \rightarrow \text{Dynamic}$$

✓ Causal LTI systems \* (condition on  $h[n]$ )

If  $h[n] = 0$  for  $n < 0$

the system is causal LTI system

✓ Stable LTI systems \* (condition on LTI system)

~~A system~~

A DT-LTI system is stable if and only if the impulse response  $h[n]$  is absolutely summable.

Proof ✓

$$\sum_{k=-\infty}^{\infty} |h[k]| < \infty$$

Proof: A system is Bounded input - Bounded output (BIBO) stable if the o/p is guaranteed to be bounded for every bounded input.

i.e., if  $|x[n]| \leq M_x < \infty$ ,

then  $|y[n]| \leq M_y < \infty$

We know output of an LTI system is convolution sum of input  $x[n]$  and impulse response  $h[n]$

$$y[n] = x[n] * h[n] = h[n] * x[n]$$

$$y[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

$$|y[n]| = \left| \sum_{k=-\infty}^{\infty} h[k] x[n-k] \right|$$

$$\therefore |a+b| \leq |a| + |b|$$

$$y[n] \leq \sum_{k=-\infty}^{\infty} |h[k] x[n-k]|$$

$$\therefore |ab| = |a||b|$$

$$y[n] \leq \sum_{k=-\infty}^{\infty} |h[k]| |x[n-k]|$$

$$\text{as } |x[k]| \leq M_x < \infty$$

$$\text{the } |x[n-k]| \leq M_x.$$

Hence 
$$y[n] \leq M_x \sum_{k=-\infty}^{\infty} |h[k]|$$

Hence output is bounded, provided impulse response  $h[n]$  is absolutely summable.

$\therefore$  An LTI system is stable if and only if, its impulse response is absolutely summable.

$$\sum_{k=-\infty}^{\infty} |h[k]| < \infty$$


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- Ex:
- $h[n] = 2^n u[-n]$  : not memoryless, not causal, stable
  - $h[n] = e^{2n} u[n-1]$  : not memoryless, causal, ~~not~~ stable
  - $h[n] = \left(\frac{1}{2}\right)^n u[n]$  ; not memoryless, causal, stable
  - $h[n] = \cos\left(\frac{\pi}{2}n\right) u[n+3]$  ;  
not memoryless, not causal, not stable.

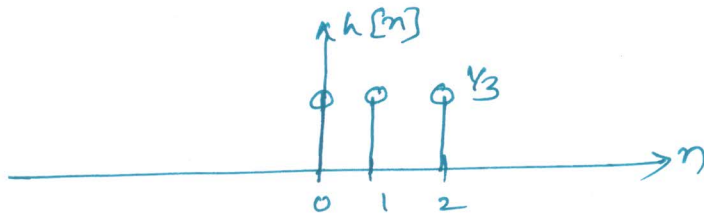
ex: show that a 3-sample moving-average system is stable

sol:  $y[n] = \frac{1}{3}x[n] + \frac{1}{3}x[n-1] + \frac{1}{3}x[n-2]$

find  $h[n]$ :

if  $x[n] = \delta[n]$ , then  $y[n] = h[n]$

$\therefore h[n] = \frac{1}{3}\delta[n] + \frac{1}{3}\delta[n-1] + \frac{1}{3}\delta[n-2]$



$\therefore h[n] = \left\{ \frac{1}{3}, \frac{1}{3}, \frac{1}{3} \right\}$

Stability:

$S = \sum_{k=-\infty}^{\infty} |h[k]| = \sum_{k=0}^2 |h[k]| = \frac{1}{3} + \frac{1}{3} + \frac{1}{3} = 1$

$S < \infty$  ;  $h[n]$  is absolutely summable.  
Hence stable system

Ex:

consider the DT system  $y[n] = r^n x[n]$

Comment on its stability for  $r > 1$

Ans: Unstable

sol:

if  $x[n] = \delta[n]$  ;  $y[n] = h[n]$

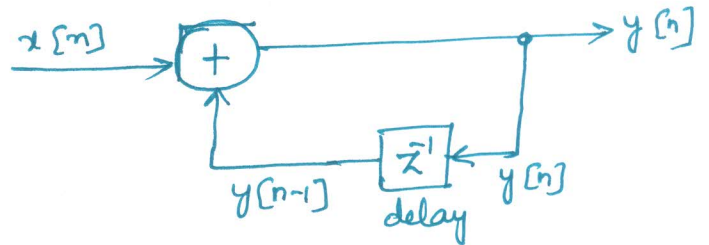
$\therefore h[n] = r^n \delta[n]$

$n=0$  ;  $h[0] = r^0 \delta[0] = 1$

$h[1] = r^1 \delta[1] = 0$

Ex: Check the stability of the DT system

$$y[n] = a y[n-1] + x[n] \quad ; \text{ Assume initially relaxed.}$$



sol:  $y[n] = a y[n-1] + x[n]$

if  $x[n] = \delta[n]$  then  $y[n] = h[n]$

$$\therefore h[n] = a h[n-1] + \delta[n]$$

$$\underline{n=0} ; h[0] = a h[-1] + \delta[0] = 0 + 1 = 1$$

$$\underline{n=1} ; h[1] = a h[0] + \delta[1] = a \cdot 1 + 0 = a$$

$$\underline{n=2} ; h[2] = a [h[1]] + \delta[2] = a \cdot [a] + 0 = a^2$$

$$\underline{n=3} ; h[3] = a h[2] + \delta[3] = a [a^2] + 0 = a^3$$

$$\vdots$$

$$h[n] = a^n ; n \geq 0$$

$$\therefore h[n] = a^n u[n].$$

Stability:  $S = \sum_{k=0}^{\infty} |h[k]| = \sum_{k=0}^{\infty} |a^k| = \frac{1}{1-|a|}$

It converges only if  $|a| < 1$

$\therefore$  The given system is stable only when  $|a| < 1$

Note Ex:  $y[n] = 0.5 y[n-1] + x[n]$  is stable system  
 $y[n] = 2 y[n-1] + x[n]$  is an unstable system.



✓ Investigate the causality and stability of the following systems:

①  $h[n] = 2^n u[n-1]$  ;  $\therefore$  it is causal.

$$S = \sum_{n=-\infty}^{\infty} |h[n]| = \sum_{n=1}^{\infty} 2^n = 2+4+8+\dots = \infty$$

Hence Unstable

②  $y[n] = 2x[n+1] + 3x[n] - x[n-1]$

↳ Noncausal

$$h[n] = 2\delta[n+1] + 3\delta[n] - \delta[n-1]$$

$$\therefore h[n] = \{ 2, 3, -1 \}$$

$$\therefore S = \sum_n |h[n]| = 2+3+(1) = \underline{6} \quad \text{Hence stable}$$

③  $h[n] = (-0.5)^n u[n]$   
causal

$$S = \sum_n |h[n]| = \sum_{n \geq 0} (-0.5)^n = 1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots = \frac{1}{1-\frac{1}{2}} = \underline{\underline{2}}$$

Hence stable

④  $h[n] = \{ 3, 2, 1, 1, 2 \}$

Noncausal

$$S = \sum h[n] = 3+2+1+1+2 = 9 ; \text{ Hence stable}$$

⑤  $h[n] = (-0.5)^n u[-n]$   
non-causal

$$S = \sum_{n=-\infty}^{\infty} (-0.5)^n u[-n] = \sum_{n=-\infty}^0 \left(-\frac{1}{2}\right)^n = \sum_{n=0}^{\infty} \text{ stable}$$

⑥  $h[n] = (0.5)^{|n|}$

Noncausal and stable

(two-sided decaying exponential)